



Designation: A977/A977M – 07 (Reapproved 2020)

Standard Test Method for Magnetic Properties of High-Coercivity Permanent Magnet Materials Using Hysteresigraphs¹

This standard is issued under the fixed designation A977/A977M; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon (ϵ) indicates an editorial change since the last revision or reapproval.

1. Scope

1.1 This test method covers how to determine the magnetic characteristics of magnetically hard materials (permanent magnets), particularly their initial magnetization, demagnetization, and recoil curves, and such quantities as the residual induction, coercive field strength, knee field, energy product, and recoil permeability. This test method is suitable for all materials processed into bulk magnets by any common fabrication technique (casting, sintering, rolling, molding, and so forth), but not for thin films or for magnets that are very small or of unusual shape. Uniformity of composition, structure, and properties throughout the magnet volume is necessary to obtain repeatable results. Particular attention is paid to the problems posed by modern materials combining very high coercivity with high saturation induction, such as the rare-earth magnets, for which older test methods (see Test Method [A341/A341M](#)) are unsuitable. An applicable international standard is IEC Publication 60404-5.

1.2 The magnetic system (circuit) in a device or machine generally comprises flux-conducting and nonmagnetic structural members with air gaps in addition to the permanent magnet. The system behavior depends on properties and geometry of all these components and on the operating temperature. This test method describes only how to measure the properties of the permanent magnet material. The basic test method incorporates the magnetic specimen in a magnetic circuit with a closed flux path. Test methods using ring samples or frames composed entirely of the magnetic material to be characterized, as commonly used for magnetically soft materials, are not applicable to permanent magnets.

1.3 This test method shall be used in conjunction with Practice [A34/A34M](#).

1.4 The values and equations stated in customary (cgs-emu or inch-pound) or SI units are to be regarded separately as standard. Within this test method, SI units are shown in

brackets except for the sections concerning calculations where there are separate sections for the respective unit systems. The values stated in each system may not be exact equivalents; therefore, each system shall be used independently of the other. Combining values from the two systems may result in nonconformance with this test method.

1.5 The names and symbols of magnetic quantities used in this test method, summarized in [Table 1](#), are those generally accepted by the industry.

1.6 This test method is useful for magnet materials having H_{ci} values between about 100 Oe and 35 kOe [8 kA/m and 2.8 MA/m], and B_r values in the approximate range from 500 G to 20 kG [50 mT to 2 T]. High-coercivity rare-earth magnet test specimens may require much higher magnetizing fields than iron-core electromagnets can produce. Such samples must be premagnetized externally and transferred into the measuring yoke. Typical values of the magnetizing fields, H_{mag} , required for saturating magnet materials are shown in [Table A2.1](#).

1.7 *This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety, health, and environmental practices and determine the applicability of regulatory limitations prior to use.*

1.8 *This international standard was developed in accordance with internationally recognized principles on standardization established in the Decision on Principles for the Development of International Standards, Guides and Recommendations issued by the World Trade Organization Technical Barriers to Trade (TBT) Committee.*

2. Referenced Documents

2.1 *ASTM Standards:*²

[A34/A34M Practice for Sampling and Procurement Testing of Magnetic Materials](#)

[A340 Terminology of Symbols and Definitions Relating to Magnetic Testing](#)

¹ This test method is under the jurisdiction of ASTM Committee [A06](#) on Magnetic Properties and is the direct responsibility of Subcommittee [A06.01](#) on Test Methods.

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² For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

TABLE 1 Symbols, Quantities, and Units

NOTE 1—IEC nomenclature calls B_r “remanence,” when B_r represents the B at $H = 0$ of the outermost hysteresis loop, and it calls B_r “remanent magnetic induction” for B at $H = 0$ at smaller loops.

Symbol	Quantity	SI Unit	Customary cgs-emu
A_t	Cross section of search coil	[m ²]	cm ²
B_d	Magnetic induction at BH_{\max}	[T]	G
B_{rec}	Magnetic induction at low point of recoil loop	[T]	G
B_r	Magnetic induction at remanence	[T]	G
d_1	Diameter of pole piece	[m]	cm
d_2	Diameter of homogeneous field	[m]	cm
H_d	Magnetic field strength at BH_{\max}	[A/m]	Oe
H_p	Magnetic field strength at low point of recoil loop	[A/m]	Oe
l	Distance between pole faces	[m]	cm
l_r	Length of test sample	[m]	cm
N	Number of turns of test coil		
e	Voltage induced in test coil	V	V
d	Total air gap between test sample and pole faces	[m]	cm
μ_0	A constant with value $\mu_0 = 4\pi \cdot 10^{-7}$ H/m		
μ_{rec}	Recoil permeability		

[A341/A341M Test Method for Direct Current Magnetic Properties of Soft Magnetic Materials Using D-C Permeameters and the Point by Point \(Ballistic\) Test Methods](#)
[E177 Practice for Use of the Terms Precision and Bias in ASTM Test Methods](#)

2.2 *Magnetic Materials Procedure Association Standard*.³
[MMPA No. 0100–00 Standard Specifications for Permanent Magnet Materials](#)

2.3 *International Electrotechnical Commission Document*.⁴
[Publication 60404-5 Magnetic Materials– Part 5: Permanent Magnet \(Magnetically Hard\) Materials – Methods of Measurement of Magnetic Properties](#)

3. Terminology

3.1 Basic magnetic units are defined in Terminology [A340](#) and MMPA No. 0100–00. Additional definitions with symbols and units are given in [Table 1](#) and [Figs. 1-3](#) of this test method.

4. Significance and Use

4.1 This test method is suitable for magnet specification, acceptance, service evaluation, quality control in magnet production, research and development, and design.

4.2 When a test specimen is cut or fabricated from a larger magnet, the magnetic properties measured on it are not necessarily exactly those of the original sample, even if the material is in the same condition. In such instances, the test results must be viewed in context of part performance history.

³ Available from Magnetic Materials Producers Association, 8 S. Michigan Ave., Suite 1000, Chicago, IL 60603.

⁴ Available from International Electrotechnical Commission (IEC), 3 rue de Varembe, P.O. Box 131, CH-1211, Geneva 20, Switzerland.

4.3 Tests performed in general conformity to this test method and even on the same specimen, but using different test systems, may not yield identical results. The main source of discrepancies are variations between the different test systems in the geometry of the region surrounding the sample, such as, size and shape of the electromagnet pole caps (see [Annex A1](#) and [Appendix X1](#)), air gaps at the specimen end faces, and especially the size and location of the measuring devices for H and B or for their corresponding flux values (Hall-effect probes, inductive sensing coils). Also important is the method of B calibration, for example, a volt-second calibration of the fluxmeter alone versus an overall system calibration using a physical reference sample. The method of B and H sensing should be indicated in test reports (see [Section 9](#)).

5. Measuring Methods and Apparatus

5.1 Measuring Flux and Induction (Flux Density):

5.1.1 In the preferred B -measuring method, the total flux is measured with a sensing coil (search coil) that surrounds the test specimen and is wound as closely as possible to the specimen surface. Its winding length should be no more than a third of the specimen length, preferably less than one fifth, and must be centered on the specimen. The leads shall be twisted tightly. As the flux changes in response to sweeping the applied field, H , the total flux is measured by taking the time integral of the voltage induced in this coil. This measurement is taken with a fluxmeter. Modern hysteresigraphs use electronic integrating fluxmeters that allow convenient continuous integration and direct graphic recording of magnetization curves. If the signal is large enough, high-speed voltage sampling at the coil and digital integration is also possible.

5.1.2 The magnetic induction B is determined by dividing the total flux by the area-turns product NA of the B -sensing coil. For permanent magnets in general, and especially for high-coercivity materials, an air-flux correction is required (see [5.1.5](#)).

5.1.3 The total error of measuring B shall be not greater than $\pm 2\%$.

5.1.4 The change of magnetic induction, $\Delta B = B_2 - B_1$, in the time interval between the times t_1 and t_2 is given as follows:

$$\Delta B = (10^8/AN) \int_{t_1}^{t_2} e \, dt \text{ (customary units)} \quad (1)$$

$$\Delta B = (1/AN) \int_{t_1}^{t_2} e \, dt \text{ (SI units)} \quad (2)$$

where:

B = magnetic induction, G [T];
 A = cross-sectional area of the test specimen, cm² [m²];
 N = number of turns on the B -sensing coil;
 e = voltage induced in the coil, V;
 t = time, s; and
 $\int_{t_1}^{t_2} e \, dt$ = voltage integral = flux, V-s [Weber].

5.1.5 The change in the magnetic induction shall be corrected to take into account the air flux outside the test specimen that is linked by the sensing coil. The corrected change, B_{corr} , is given as follows:

$$\Delta B_{\text{corr}} = (10^8/AN) \int_{t_1}^{t_2} e \, dt - \Delta H (A_r - A)/A \text{ (customary units)} \quad (3)$$

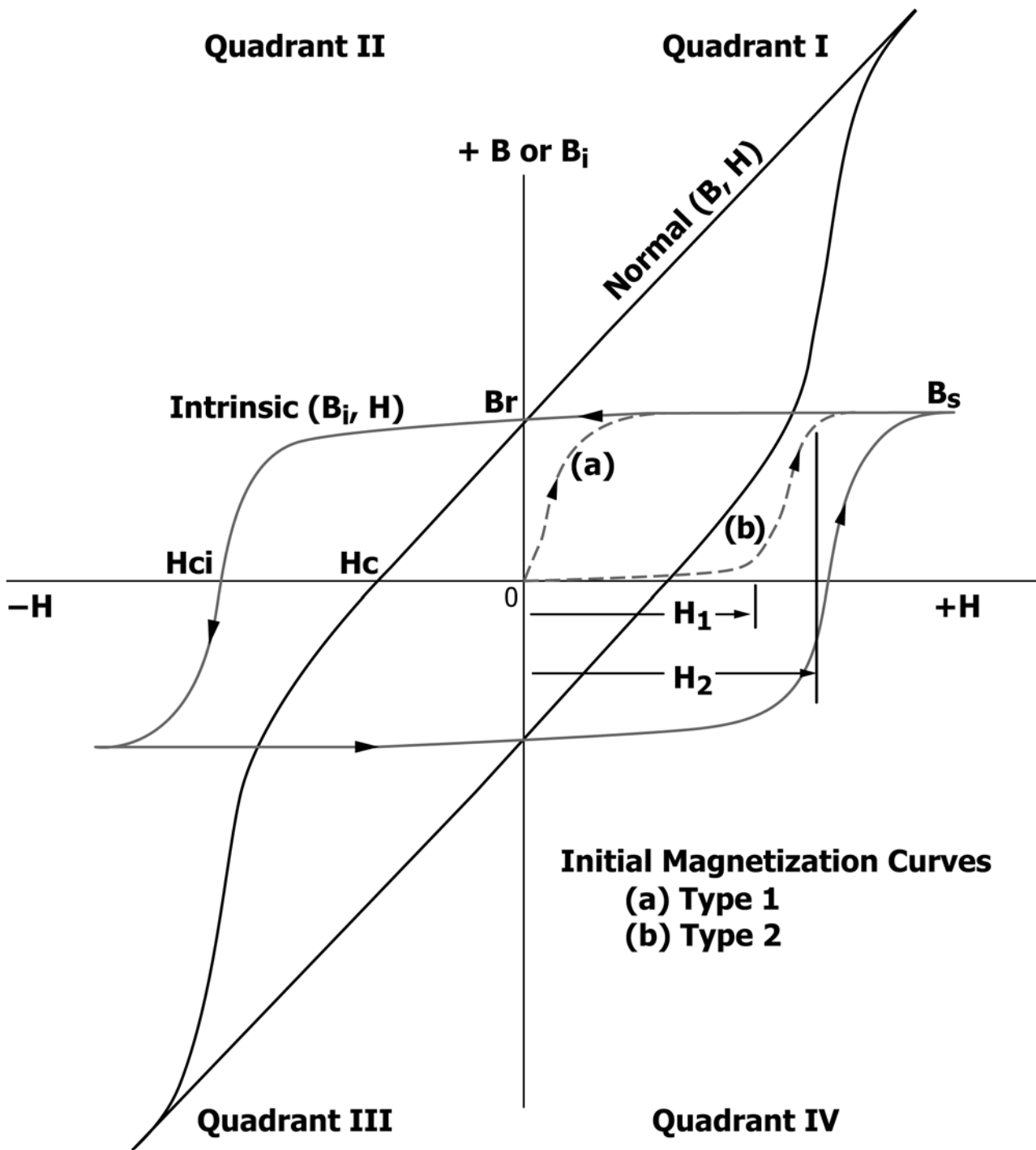


FIG. 1 Normal and Intrinsic Hysteresis Loops and Initial Magnetization Curves for Permanent Magnet Materials Illustrating Two Extremes of Virgin Sample Behavior

$$\Delta B_{\text{corr}} = (1/AN) \int_{t_1}^{t_2} e \, dt - \mu_0 \Delta H (A_t - A)/A \text{ (SI units)} \quad (4)$$

where:

- A = average cross-sectional area of the sensing coil, cm^2 [m^2];
- ΔH = change in field from t_1 until t_2 , Oe [A/m]; and
- μ_0 = magnetic constant [$4\pi \cdot 10^{-7} \text{ H/m}$].

5.2 Determining Intrinsic Induction :

5.2.1 For high-coercivity magnets, it is more convenient to sense directly an electrical signal proportional to the intrinsic induction, derive the average B_i by dividing this flux by the area-turns product of the surrounding B coil, and to plot B_i versus H . B then is obtained by mathematical or electronic addition of H to B .